

ON TIME CONSISTENCY,
PARETO-OPTIMALITY [& EQUILIBRIUM] IN A
MODEL WITH HETEROGENEOUS
QUASI-HYPERBOLIC DISCOUNTING AGENTS

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A CLASSICAL FABLE

- Heterogeneous Aesop/La Fontaine's flavoured Grasshoppers and Ants-like Environment with distinct time perceptions.
 - 1 Short-sighted Grasshoppers are just concerned by today.
 - 2 Far-Sighted ants think about the future and do save most of their income.
 - 3 After a succession of generations, the ants would hold the whole wealth while the Grasshoppers would be in the need to reimburse their debts.

- Role for a benevolent social planner?
 - 1 Is it to follow the ants or the Grasshoppers perception?
 - 2 Is it to rely on the ants or on the Grasshoppers in order to determine a welfare criterion?
 - 3 Upon the existence of some irrational behaviour, should a benevolent planner constrain the agents to follow behaviours that differ from their own choice and build some sort of happiness against their own will.

SIMPLE ANSWERS & PROBLEMS AT STAKE

■ Simple Answers:

- 1 Benevolent planner maximises long-run welfare with the utilities of the agent, planner ends up with a greater weight for the positive long-run valuation of the ants.
- 2 Even though the grasshoppers are neglected and only the ants are taken into account, sounds like a Pareto-Optimal solution.

■ Three issues at stake:

- 1 How does a centralized planning solution relate to Time Consistency?
- 2 How does a centralized planning solution relate to Pareto-Optimality for the Agents?
- 3 [How does a centralised solution relate to the equilibrium solution?]

SOME NEW COUNTER-FABLES (I)

- Environnement where Grasshoppers and ants do co-exist:
 - 1 The Negishi flavor social optimum as defined by the benevolent planner is not time-consistent.
 - 2 Would it be stated at another period, it would lead to another solution.
- New solution concept for the social optimum of the benevolent planner.
 - 1 Pareto Optima constrained to be time-consistent.
 - 2 A long run where grasshoppers and ants end up having the same consumption.
 - 3 A long run where the time perception / preference corresponds to an average of the grasshoppers and ants approaches.

SOME NEW COUNTER-FABLES (II)

- Environment where grasshoppers would further assume some sort of irrationality:
 - 1 Grasshoppers procrastinate and delay up to tomorrow their savings decision.
 - 2 Today grasshoppers disagree with tomorrow ones.
 - 3 A grasshopper is now considered as a dynasty / sequence of successive incarnations, a given period incarnation being in charge of the consumption and savings decision for that period.

SOME NEW COUNTER-FABLES (II *bis*)

- Two concepts of social optimum are introduced:
 - 1 A dynasties approach.
 - (i) Appropriately weight all of the utilities of the successive incarnations in order to bring them back to the ants preferences.
 - (ii) All of the issues that spring from some degree of irrationality or heterogeneity are circumvented but the grasshoppers preferences are somewhat forgotten.
 - 2 An heterogeneity-based approach.
 - (i) Pareto Optima are constrained to be time-consistent.
 - (ii) A long run where the time perception / preference of the benevolent planner corresponds to an average of the grasshoppers dynasties and ants approaches.
 - (iii) A Happy Ending for both grasshoppers and ants, a new epilogue for the fable!

THE ENVIRONMENT

QUASI-GEOMETRIC DISCOUNTING

- Given agent $i \in \{1, 2, \dots, n\}$: *self* at time $t \in \mathbb{N}$ ranks consumption sequences according to:

$$u(c_t^i) + \beta_i \left[\sum_{\tau=1}^{+\infty} (\delta_i)^\tau u(c_{t+\tau}^i) \right], \beta_i > 0, \delta_i \in]0, 1[. \quad (2)$$

- With a present bias ($\beta_i \neq 1$), decisions of agent $i \in \{1, 2, \dots, n\}$ stem from the Nash equilibrium of a strategic game between the successive *selves*.
- ASSUMPTION $u(\cdot)$ is defined on \mathbb{R}_+ , of class \mathcal{C}^2 , with $Du(c) > 0$, $D^2u(c) < 0$, for $c > 0$ and $Du(0) = +\infty$, $Du(+\infty) = 0$, $\delta_i \in]0, 1[$, $i = 1, \dots, n$ and $\delta_1 > \dots > \delta_n$.
- Temporally inconsistent preferences (though consistent starting from date $t \geq 1$).

THE ENVIRONMENT

EXTRA RESTRICTIONS & RESSOURCE CONSTRAINT

- Environment with n heterogeneous agents
- $1 > \delta_1 > \delta_2 > \dots > \delta_n > 0$.
- Agents utilities are weighted according to factors $\lambda_1, \dots, \lambda_n$ within the Negishi-type objective of the benevolent planner.

INTRUDUCING AN OPTIMUM

ISSUES AT STAKE

- Two essential difficulties:
 - 1 For $\beta_i \neq 1$, temporal inconsistency of individual preferences and present biased agents.
 - 2 For $\beta_i = 1$, present unbiased agents but heterogeneity in the parameter δ_i results in a temporal inconsistency in the objective of the Centralized Planner (Drugeon & Wigniolle [JME, 2016]).

THE CONSISTENCY ISSUE [$\beta_i = 1$, Two agents case, Equal weights]

- Comparison between two distinct incarnations of the social planner (two agents case and identical weights).

1 the date 0-incarnation objective function:

$$\sum_{t=0}^{+\infty} \sum_{i=1}^2 (\delta_i)^t u(c_t^i)$$

2 the date t -incarnation objective function.

a/ The inter-temporal utility function of agent i from date t on:

$$\sum_{\tau=0}^{+\infty} (\delta_i)^\tau u(c_{t+\tau}^i).$$

b/ The objective of date t -incarnation becomes:

$$\sum_{\tau=0}^{+\infty} \sum_{i=1}^2 (\delta_i)^\tau u(c_{t+\tau}^i).$$

THE CONSISTENCY ISSUE [$\beta_i = 1$, Two agents case]

- Comparison between 1 and 2.b/

- 1 Date 0-incarnation of the centralised planner, period t element:

$$(\delta_1)^t [u(c_t^1) + (\delta_2/\delta_1)^t u(c_t^2)].$$

- 2 Date t -incarnation of the social planner, period t element

$$[u(c_t^1) + u(c_t^2)].$$

- Heterogeneity of discount factors ($\delta_1 \neq \delta_2$) \implies objective of the incarnation at date t of the social planner is not consistent with the one of its incarnation at date 0.
- Would the incarnation at date 0 of the social planner be in position to take the whole sequence of decisions from date 0 to $+\infty$, he would select for date t a class of decisions that *differ* from its incarnation at date t .
- Heterogeneity in discount factors hence leads to *temporal inconsistency* in the sequential incarnations of the planner's choices.

CENTRALIZED PLANNING SOLUTION

DEFINITION?

- Exists distinct ways to cope with this twofold temporal inconsistency
 - 1 $\beta_i \neq 1$
 - 2 $\delta_1 \neq \delta_2$ for $\beta_i = 1$
- Two main definitions (with many variants and many different properties!) for the Centralized Planner (aiming at Time Consistency):
 - 1 A Centralized Planning Solution Based upon Dynasties of Selves.
 - 2 A Planner Incarnation for the Current Selves.

THE DYNASTIES-BASED CENTRALIZED PLANNER SOLUTION

DEFINITION FOR THE SINGLE AGENT/DYNASTY CASE

- Agent with preference parameters (β, δ) :

$$u(c_t) + \beta \left[\sum_{\tau=1}^{+\infty} (\delta)^\tau u(c_{t+\tau}) \right], \beta > 0, \delta \in]0, 1[.$$

- Negishi-like approach over a given dynasty
- Benevolent planner takes a weighted average of the objective functions of the different selves.
- Extra constraint: *Time-consistency* constraint on the optimal programs \implies Seeks an exponentially discounted form.

THE FULLY CONSISTENT CENTRALIZED SOLUTION

DEFINITION FOR THE SINGLE AGENT CASE

- Weights, denoted as $(\eta_t)_{t \in \mathbb{N}}$, for $\eta_t > 0$ for every $t \in \mathbb{N}$: defined such that the Centralized Planner's criterion corresponds to a weighted average of utilities at any date with an exponential coefficient $\gamma \in]0, 1[$.
- Planner considers (I)

$$\sum_{t=0}^{+\infty} \eta_t \left[u(c_t) + \beta \sum_{\tau=1}^{+\infty} u(c_{t+\tau}) \delta^\tau \right]$$

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- One looks for a sequence of weights $(\eta_t)_{t \in \mathbb{N}}$ such that the planner's criterion formulates along (II):

$$\eta_0 \sum_{t=0}^{+\infty} \gamma^t u(c_t)$$

THE DYNASTIES-BASED CENTRALIZED PLANNER SOLUTION

A FIRST RESULT FOR THE SINGLE AGENT CASE

PROPOSITION .1

—Let γ be such that $\gamma \in [\delta, 1[$. The objective

$$\sum_{t=0}^{+\infty} \eta_t \left[u(c_t) + \beta \sum_{\tau=1}^{+\infty} u(c_{t+\tau}) \delta^\tau \right]$$

of the centralised planner corresponds to the exponentially discounted form

$$\eta_0 \sum_{t=0}^{+\infty} \gamma^t u(c_t)$$

if and only if the weights η_t are defined according to

$$\eta_t = \eta_0 \left\{ \frac{\gamma - \delta}{\gamma - \delta(1 - \beta)} \gamma^t + \frac{\beta \delta}{\gamma - \delta(1 - \beta)} [\delta(1 - \beta)]^t \right\}.$$

THE DYNASTIES-BASED CENTRALIZED PLANNER SOLUTION

A COMMENT FOR THE SINGLE AGENT CASE

- This proposition generalizes Galperti & Strulovici [2015] where $\gamma = \delta$.
- Values of γ such that $\gamma \in]\delta, 1[$ are also admissible.

UNDERSTANDING PROPOSITION 1

THE BENCHMARK $\beta_1 = 1$ CONFIGURATION

- Selecting weightings η_t^i to the incarnations of the agents i sums up to to modify the discount factor from δ_i to γ for the social planner.
- Clear for $\beta_i = 1$ for which the weightings would indeed simplify to

$$\eta_t^i = \beta_0^i \cdot \frac{(\gamma - \delta_i)}{\gamma} \gamma^t$$

for every $t \geq 1$.

- Selecting a sum weighed by η_t^i of the successive incarnations of agent i , the planner would indeed transform the agent's discount factor δ_i to a value of γ .
- Proposition 1 allows for recovering temporal consistency for the objective of the social planner but this only be achieved through a *modification* of the preferences of the agents.

UNDERSTANDING PROPOSITION 1

AN UPCOUNTING $\beta_1 > 1$ CONFIGURATION

- Under some extra conditions, this result can be extended to a configuration where $\beta_i > 1$.
- To be checked: $\eta_t^i > 0$ keeps on prevailing for every t .
- Argument of the proof of Proposition 1 implies:

$$\eta_1 = (\gamma - \beta\delta)\eta_0.$$

■ Restrictions:

- 1 $\gamma > \beta\delta$ and thus $\gamma > \delta$. Sufficient for the satisfaction of $\eta_t > 0$ for every t .
- 2 Check that, for every t , the inequation:

$$(\gamma - \delta)\gamma^t + \beta\delta[\delta(1 - \beta)]^t > 0.$$

True for even values of t plus corresponds to $(\gamma + \delta\beta - 1)(\gamma - \beta\delta) > 0$ for odd values of t . Also satisfied and establishes the overall property for the odd values of t .

THE FULLY CONSISTENT SOLUTION

THE HETEROGENEOUS AGENTS ARGUMENT

- n agents characterized by pairs (β_i, δ_i) , $i = 1, \dots, n$.

$$u(c_t^i) + \beta_i \left[\sum_{\tau=1}^{+\infty} (\delta_i)^\tau u(c_{t+\tau}^i) \right], \beta_i > 0, \delta_i \in]0, 1[.$$

- Objective of the social planner defined through a double summation over n agents made of an infinity of selves:

$$\sum_{i=1}^n \sum_{t=0}^{+\infty} r_t^i \left[u(c_t^i) + \beta_i \sum_{\tau=1}^{+\infty} u(c_{t+\tau}^i) (\delta^i)^\tau \right]$$

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

A HETEROGENOUS AGENTS RESULT

PROPOSITION .2

—Let γ be such that $\gamma \in [\max_{i \in \{1, \dots, n\}}(\delta_i), 1[$. If the weights $(\eta_t^i)_{t \in \mathbb{N}}$ are such that, for every $i \in \{1, \dots, n\}$,

$$\eta_t^i = \eta_0^i \left\{ \frac{(\gamma - \delta_i)}{\gamma - \delta_i(1 - \beta_i)} \gamma^t + \frac{\beta_i \delta_i [\delta_i(1 - \beta_i)]^t}{\gamma - \delta_i(1 - \beta_i)} \right\},$$

then the objective

$$\sum_{t=0}^{+\infty} \eta_t \left[u(c_t) + \beta \sum_{\tau=1}^{+\infty} u(c_{t+\tau}) \delta^\tau \right]$$

of the centralized planner writes down along

$$\sum_{t=0}^{+\infty} \gamma^t \left\{ \sum_{i=1}^n \eta_0^i u(c_t^i) \right\},$$

UNDERSTANDING PROPOSITION 2

COMMENTS (I)

- Proposition 2: brings the objective back to a standard (discounted) centralized one.
- Proposition 1: for agent $i \in \{1, \dots, n\}$, possible to derive a temporally consistent planner's objective with a coefficient given by $\gamma \geq \delta_i$.

UNDERSTANDING PROPOSITION 2

COMMENTS (II)

- For n agents, temporal consistency is only available if the same value of γ is retained for all of the agents, that limits to the selection of $\gamma \geq \max_{i \in \{1, \dots, n\}} (\delta_i)$.
- Allowing for distinct values of γ_i for every agent would result in a planner's objective of the following form:
- Drugeon & Wigniolle [JME, 2016] have analyzed such an objective and illustrated the involved temporal inconsistency issue.

THE DYNASTIES-BASED CENTRALIZED PLANNER SOLUTION

THE OPTIMIZATION PROGRAM & THE LONG RUN

- The maximization program states as:

$$\max \sum_{t=0}^{+\infty} \gamma^t \left\{ \sum_{i=1}^n \eta_{l_0}^i u(c_t^i) \right\}$$
$$\text{s.t. } K_{t+1} + \sum_{i=1}^n c_t^i = F(K_t, 1) + (1 - \mu)K_t, K_0 \text{ given.}$$

- Standard problem.
- Economy converges towards the modified golden rule K^* in the long run:

$$D_K F(K^*, 1) + (1 - \mu) = \frac{1}{\gamma}.$$

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

COMMENTS ON THE LONG RUN

- With such a definition for the objective function, solution is:
 - 1 Pareto optimal for the successive incarnations of the agents.
 - 2 Temporally consistent.
- Drawbacks:
 - 1 Rate of time preference of the planner is unrelated to the ones of the agents for $\gamma > \max_{i \in \{1, \dots, n\}}(\delta_i)$.
 - 2 Rate of time preference of the planner has the one of the most patient agent for $\gamma = \max_{i \in \{1, \dots, n\}}(\delta_i)$.

THE DYNASTIES-BASED CENTRALIZED PLANNER SOLUTION

STATUS OF THE PARETO OPTIMAL SOLUTION FOR $\gamma_i = \delta_i$

- Along the specialisation of Galperti & Strulovici to $\gamma_i = \delta_i$, the planner's solution is available as:

$$\sum_{i=1}^n \eta_{i0}^i \left\{ \sum_{t=0}^{+\infty} (\delta_i)^t u(c_t^i) \right\}.$$

- Pareto optimal but time inconsistent solution.
- Planner's maximization at a later date: distinct solution.

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

STATUS OF THE PARETO OPTIMAL SOLUTION

- Way of circumventing time-inconsistency: Drugeon & Wigniolle [JME, 2016].
 - 1 *Imposition* of temporal consistency for the choices of the successive incarnations of the social planner.
 - 2 By assumption: decision rules will be functions that unequivocally depend on the state variable—the capital stock—under consideration:

$$c_t^i = \vartheta_C^i(K_t).$$

- 3 The solution then comes from a strategic game between the successive incarnations of the planner: *the incarnation at date t determines the best resource allocation at t , having taken into account that all future incarnations of the planner will apply the strategy $c_{t+\tau}^i = \vartheta_C^i(K_{t+\tau})$.*
- 4 This assumption hence ensures *time consistency* in the optimal choices of the successive social planners.

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

AN ALTERNATIVE TIME-CONSISTENT APPROACH

- The solution concept for this game is similar to the one that was used in the literature on time inconsistency of the consumer problem initiated by Phelps and Pollack
- The social planner is therein viewed as successive incarnations and the decision at date t is taken by the t -th incarnation. Phelps and Pollack went on labelling their equilibrium concept as a *Cournot-Nash Equilibrium*.
- Literature on hyperbolic discounting, various names.
- Judd introduces the seemingly most precise terminology for this equilibrium that is referred as a *continuous differentiable Nash equilibrium*.
- The most common name for this solution concept is however the one of *Markov equilibrium*—vid., e.g, Harris and Laibson or Krussel and Smith. At times referred in an intuitive way as describing a *sophisticated behaviour*.

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

STATUS OF THE PARETO OPTIMAL SOLUTION

- $J^i(K_t)$: utility over time of agent i from period $t \geq 0$ on, with a rule $\vartheta_{t+\tau}^i = \vartheta_C^i(K_{t+\tau})$, $\tau \geq 0$, starting with a level of the capital stock given by K_t :

$$J^i(K_t) = \sum_{\tau=0}^{+\infty} (\delta_i)^\tau u[\vartheta_C^i(K_{t+\tau})]$$

for $\{K_{t+\tau}\}_{\tau \geq 0}$ recursively defined through

$$K_{t+\tau+1} = F(K_{t+\tau}, 1) + (1 - \eta)K_{t+\tau} - \sum_{i=1}^2 \vartheta_C^i(K_{t+\tau})$$

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

BELLMAN-LIKE EQUATIONS

$$W(K_t) := \sum_{i=1}^2 J^i(K_t),$$

$$W^\Delta(K_t) := \sum_{i=1}^2 \delta_i J^i(K_t),$$

- $\Delta := (\delta_1, \delta_2)$: vector of heterogeneous discount rates.
- Functions $\vartheta_C^i(K_t)$ then solve:

$$W(K_t) = \max_{\{c_t^i\}} \left\{ \sum_{i=1}^2 u(c_t^i) + W^\Delta(K_{t+1}) \right\} \quad \text{s.t.} \quad K_{t+1} = F(K_t, 1) + (1 - \eta)K_t - \sum_{i=1}^2 c_t^i$$

- Remark: for $\delta_1 = \delta_2 = \delta$, one recovers $W^\Delta(K_t) = \delta W(K_t)$, previous program uncovers a recursive formulation grounded upon the satisfaction of a Bellman Equation.

THE DYNASTIES-BASED CENTRALIZED PLANNER

SOLUTION

THE LONG RUN

- 1 Converges towards a modified golden rule where all discount factors come into play:

$$D_K F(K, 1) + (1 - \mu) = \left\{ \sum_{i=1}^n \frac{\delta_i D \vartheta_C^i(K)}{1 - \delta^i [D_K F(K, 1) + 1 - \mu - \sum_{i=1}^n D \vartheta_C^i(K)]} \right\}^{-1} \\ \times \left\{ \sum_{i=1}^n \frac{D \vartheta_C^i(K)}{1 - \delta^i [D_K F(K, 1) + 1 - \mu - \sum_{i=1}^n D \vartheta_C^i(K)]} \right\};$$

- 2 Ensued solution is only temporally consistent constrained Pareto Optimal.

THE ALTERNATIVE: A PLANNER INCARNATION FOR THE CURRENT SELVES

DEFINITION

- Alternative formulation for the objective of the Benevolent Planner.
- Assumed date- t incarnation of the centralized planner maximizes a weighted average of the objectives of the incarnations of the agents at date t .
- Its objective formulates as:

$$\sum_{i=1}^n \eta^i u(c_t^i) + \sum_{i=1}^n \eta^i \beta^i \sum_{\tau=1}^{+\infty} (\delta_i)^\tau u(c_{t+\tau}^i)$$

A PLANNER SOLUTION FOR THE CURRENT SELVES

TEMPORALLY INCONSISTENT SOLUTION

- Date- t incarnation of the centralized planner maximizes the objective

$$\sum_{i=1}^n \eta^i u(c_t^i) + \sum_{i=1}^n \eta^i \beta^i \sum_{\tau=1}^{+\infty} (\delta_i)^\tau u(c_{t+\tau}^i)$$

under the resource constraint.

- Trajectory converges towards a modified golden rule \tilde{K} such that:

$$D_K F(\tilde{K}, 1) + 1 - \mu = \frac{1}{\bar{\delta}}, \quad \bar{\delta} = \max_i (\delta_i)$$

- Most patient agent preferences determines the characteristics of the long run.
- Solution is pareto optimal for the date- t incarnations of the agents.
- Solution is not temporally consistent.

A PLANNER INCARNATION FOR THE CURRENT SELVES

TEMPORALLY CONSISTENT SOLUTION I

- Conceivable to introduce a temporally consistent solution for the objective

$$\sum_{i=1}^n \eta^i u(c_t^i) + \sum_{i=1}^n \eta^i \beta^i \sum_{\tau=1}^{+\infty} (\delta_i)^\tau u(c_{t+\tau}^i)$$

- The planner is *constrained* to decision rules that would solely depend upon the state variable K_t , or $c_t^i = \vartheta_C^i(K_t)$ and $K_{t+1} = \vartheta_K(K_t)$.
- Starting from K_0 , sequences $(c_t^i)_{t \in \mathbb{N}}$ and $(K_t)_{t \in \mathbb{N}}$ are recursively determined through:

$$K_{t+1} = F(K_t, 1) + (1 - \mu)K_t - \sum_{i=1}^n c_t^i.$$

A PLANNER INCARNATION FOR THE CURRENT SELVES INCARNATIONS

TEMPORALLY CONSISTENT SOLUTION II

- Payoff function at date t :

$$J^i(K_t) = u[\vartheta_C^i(K_t)] + \beta^i \sum_{\tau=1}^{+\infty} u[\vartheta_C^i(K_{t+\tau})](\delta_i)^\tau$$

- Other auxiliary function:

$$\mathcal{F}^i(K_t) = \sum_{\tau=0}^{+\infty} u[\vartheta_C^i(K_{t+\tau})](\delta_i)^\tau$$

- Reformulation of the payoff function:

$$J^i(K_t) = u[\vartheta_C^i(K_t)] + \beta^i \delta_i \mathcal{F}^i(K_{t+1});$$

$$J^i(K_t) = \beta_i \mathcal{F}^i(K_{t+1}) + (1 - \beta_i) u[\vartheta_C^i(K_t)].$$

Welfare functions:

$$W(K_t) = \sum_{i=1}^n \eta^i J^i(K_t), \quad \mathcal{W}(K_t) = \sum_{i=1}^n \eta^i \mathcal{F}^i(K_t) \beta_i \delta_i.$$

A PLANNER INCARNATION FOR THE CURRENT SELVES

TEMPORALLY CONSISTENT SOLUTION III

- Decision rules $\vartheta_C^i(K_t)$ and $\vartheta_K^i(K_t)$ of the social planner are solutions of the following program:

$$W(K_t) = \max \sum_{i=1}^n \eta^i u(c_t^i) + \eta^i \beta_i \delta_i \mathcal{W}(K_{t+1})$$
$$\text{s.t. } K_{t+1} = F(K_t, 1) + (1 - \mu)K_t - \sum_{i=1}^n c_t^i$$

A PLANNER INCARNATION FOR THE CURRENT SELVES

THE LONG RUN

- For $\zeta = D_K F(K, 1) + 1 - \mu$, long-run modified golden rule is defined from:

$$\sum_{i=1}^n (1 - \beta_i) D\mathfrak{D}_C^i(K) = \sum_{i=1}^n \frac{D\mathfrak{D}_C^i(K) [\zeta \beta_i \delta_i - 1]}{1 - \delta_i [\zeta - \sum_{j=1}^n D\mathfrak{D}_C^j(K)]}$$

- $\beta = 1$, equation assumes a unique solution $\zeta \in]\min_{i \in \{1, \dots, n\}}(\delta_i), \max_{i \in \{1, \dots, n\}}(\delta_i)[$
- Left neighbourhood of $\beta = 1$: existence of a unique solution.

THE LONG-RUN

PARETO-OPTIMALITY, TEMPORAL CONSISTENCY OR EQUILIBRIUM I

- 1 Temporally consistent and pareto-optimal (identically discounted agents at a rate $\gamma \geq \max_{i \in \{1, \dots, n\}}(\delta_i)$) solution:
 - All of the agents have a positive consumption in the long-run.
 - Identical for equal weights in the planner's objective.
- 2 Galperti & Strulovici [2005]'s (discounted agents at rates $\gamma_i = \delta_i$) type of solution;
 - 1 Temporally inconsistent solution: only the agent with the highest δ_i will have positive long-run consumption.
 - 2 Temporally consistent solution (Drugeon & Wigniolle [2016]'s type): all of the agents have a positive consumption in the long-run, identical for equal weights in the planner's objective.

THE LONG-RUN

PARETO-OPTIMALITY, TEMPORAL CONSISTENCY OR EQUILIBRIUM II

- 1
- 2
- 3 Date t -incarnation of the planner integrates the objectives of the current Selves at date t .
 - 1 Temporally inconsistent solution: only the most patient agent will have positive long-run consumption.
 - 2 Temporally consistent solution (Drugeon & Wigniolle [2016] 's type): all of the agents have a positive consumption in the long-run, identical for equal weights in the planner's objective.
- 4 Equilibrium solution [logarithmic preferences]
 - Only the agent with the smallest λ_i has positive consumption in the long-run, for

$$\lambda_i = \frac{1 - \delta_i}{1 - \delta_i + \beta_i \delta_i}.$$

REMAINING ISSUES (I)

- 1 Existence of the Temporally Consistent Pareto Optimal solution (dynamic game fixed point argument): no result yet available in the literature.
- 2 Understanding of the concepts of the planner solutions (Negishi weights):
 - a/ Clear for β_i (Competitive Equilibrium with Transfers).
 - b/ Unclear for β (Strategic game between the incarnations/shelves).

REMAINING ISSUES (II)

- 1 For $\beta_i = 1$, temporally consistent solution can be recovered through the following benevolent planner program:

$$\max_{\{c_t^i\}} \sum_{t=0}^{+\infty} \Delta_t \sum_{i=1}^n \lambda_i u^i(c_t^i) \quad (\mathcal{P})$$

$$\text{s.t. } K_{t+1} = F(K_t, 1) + (1 - \eta)K_t - \sum_{i=1}^n c_t^i,$$

K_0 given,

with $(\Delta_t)_{t \in \mathbb{N}}$ a sequence defined by $\Delta_0 = 1$ and $\Delta_{t+1} = \delta_t \Delta_t$ and $(\delta_t)_{t \in \mathbb{N}}$ a sequence such that, for every $t \geq 0$, $0 < \delta_n \leq \delta_t \leq \delta_1 < 1$ and $\lim_{t \rightarrow +\infty} \delta_t = \delta$.

- 2 Extra condition to be satisfied at each date:
 $\delta_t = DW^\Delta(K_{t+1}^*) / DW(K_{t+1}^*)$.
- 3 Status with $\beta_i \neq 1$?